

**Description**

The DigiFlex Performance (DP) Series digital servo drives are designed to drive brushed and brushless servomotors. These fully digital drives operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation compared to traditional PWM. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

This DP Series drive features a CANopen interface for networking and a RS-232 interface for drive configuration and setup. Drive commissioning is accomplished using DriveWare, available at www.a-m-c.com.

All drive and motor parameters are stored in non-volatile memory.

**Power Range**

Peak Current	60 A (42.4 A <sub>RMS</sub> )
Continuous Current	30 A (21.2 A <sub>RMS</sub> )
Supply Voltage	155 - 480 VAC



**Features**

- ▲ Four quadrant regenerative operation
- ▲ Space vector modulation (SVM) technology
- ▲ Fully digital state-of-the-art design
- ▲ Programmable gain settings
- ▲ Fully configurable current, voltage, velocity and position limits
- ▲ PIDF velocity loop
- ▲ PID + FF position loop
- ▲ Compact size, high power density

**MODES OF OPERATION**

- Current
- Position
- Velocity

**COMMAND SOURCE**

- ±10 V Analog
- 5V Step & Direction
- Communication Interface

**FEEDBACK SUPPORTED**

- Halls
- ±10 V Analog
- Auxiliary Incremental Encoder
- 1Vp-p Sine/Cosine Encoder

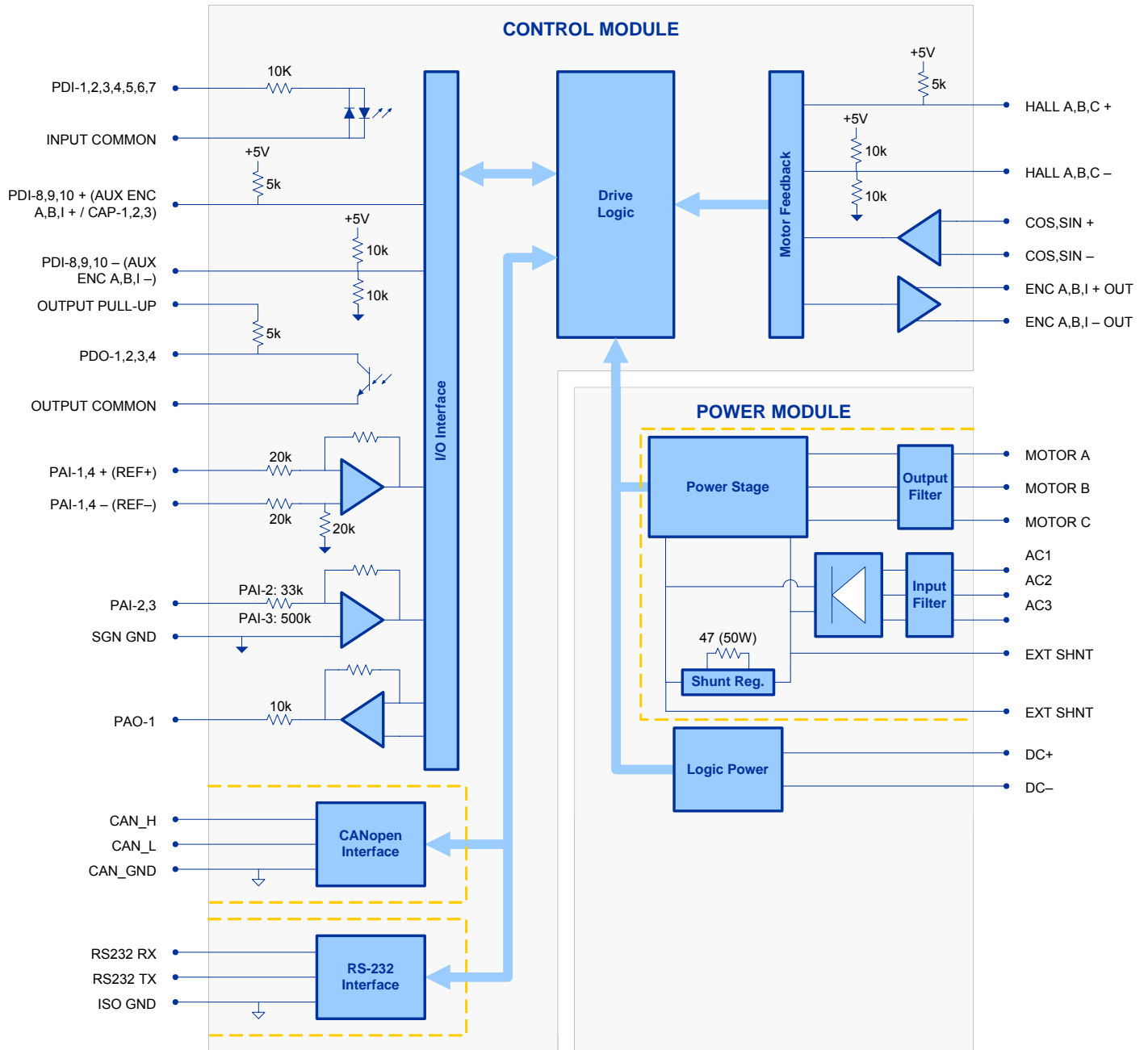
**INPUTS/OUTPUTS**

- 3 High Speed Captures
- 4 Programmable Analog Inputs
- 1 Programmable Analog Output
- 3 Programmable Digital Inputs (Differential)
- 7 Programmable Digital Inputs (Single-Ended)
- 4 Programmable Digital Outputs

**COMPLIANCES & AGENCY APPROVALS**

- RoHS
- UL/cUL Pending
- CE Pending

**BLOCK DIAGRAM**



**Approvals and Compliances**



US and Canadian safety compliance with UL 508c, the industrial standard for power conversion electronics. UL registered under file number E140173. Note that machine components compliant with UL are considered UL registered as opposed to UL listed as would be the case for commercial products.



Compliant with European CE for both the Class A EMC Directive 89/336/EEC on Electromagnetic Compatibility (specifically EN 61000-6-4:2001, EN 61000-6-2:2001, EN 61000-3-2:2000, and EN 61000-3-3:1995/A1:2001) and LVD requirements of directive 73/23/EEC (specifically EN 60204-1), a low voltage directive to protect users from electrical shock.



RoHS (Reduction of Hazardous Substances) is intended to prevent hazardous substances such as lead from being manufactured in electrical and electronic equipment.

**SPECIFICATIONS**

Power Stage Specifications		
Description	Units	Value
AC Supply Voltage	VAC	155 - 480
DC Supply Voltage	VDC	220 - 800
Over Voltage Limit	VDC	850
Under Voltage Limit	VDC	215
Logic Supply Voltage	VDC	20 - 30
Peak Output Current	A	60
Maximum Continuous Output Current	A	30
Maximum Continuous Output Power	W	24000
Maximum Power Dissipation at Continuous Current	W	1200
Internal Braking Resistor	-	Yes
Minimum Load Inductance (Line-To-Line) <sup>1</sup>	μH	3000
Switching Frequency	kHz	10
Control Specifications		
Description	Units	Value
Communication Interfaces	-	CANopen (ISO 11898-2), RS-232
Command Sources	-	±10 V Analog, 5V Step & Direction, Communication Interface
Feedback Supported	-	±10 V Analog, 1Vp-p Sine/Cosine Encoder, Auxiliary Incremental Encoder, Halls
Commutation Methods	-	Sinusoidal
Modes of Operation	-	Current, Position, Velocity
Motors Supported	-	Brushed, Brushless, Induction, Voice Coil
Hardware Protection	-	40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor), Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs (PDIs/PDOs)	-	10/4
Programmable Analog Inputs/Outputs (PAIs/PAOs)	-	4/1
Current Loop Sample Time	μs	100
Velocity Loop Sample Time	μs	100
Position Loop Sample Time	μs	100
Sin/Cos Encoder DC Offset Range	V	2 - 3.4
Maximum Sin/Cos Encoder Frequency	kHz	200
Maximum Sin/Cos Interpolation	-	128 counts per sin/cos cycle
Mechanical Specifications		
Description	Units	Value
Size (H x W x L)	mm (in)	330 x 256 x 63 (13 x 10.1 x 2.5)
Heatsink (Base) Temperature Range <sup>2</sup>	°C (°F)	0 - 65 (32 - 149)
Storage Temperature Range	°C (°F)	-40 - 85 (-40 - 185)
Cooling System	-	Natural Convection
Form Factor	-	Stand Alone
IP Rating	-	IP10
+24V LOGIC Connector	-	2-port, 5.08 mm spaced, enclosed, friction lock header
AUX COMM Connector	-	3-pin, 2.5 mm spaced, enclosed, friction lock header
AUX ENCODER Connector	-	15-pin, high-density, male D-sub
COMM Connector	-	Shielded, dual RJ-45 socket with LEDs
DC BUS Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header
FEEDBACK Connector	-	15-pin, high-density, female D-sub
I/O Connector	-	26-pin, high-density, female D-sub
MOTOR POWER Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header
POWER Connector	-	4-port, 7.62 mm spaced, enclosed, friction lock header

**Notes**

1. Low inductance motors, such as 'pancake' and 'basket-wound', require external inductors. The Minimum Load Inductance provided assumes the highest allowed bus voltage. Lower inductances are acceptable for lower bus voltages.

2. Additional cooling and/or heatsink may be required to achieve rated performance.

**PIN FUNCTIONS**

<b>+24V LOGIC - Logic Power Connector</b>			
Pin	Name	Description / Notes	I/O
1	LOGIC PWR	Logic Supply Input	I
2	LOGIC GND	Logic Supply Ground	GND

<b>AUX COMM - RS232 Communication Connector</b>			
Pin	Name	Description / Notes	I/O
1	RS232 RX	Receive Line (RS-232)	I
2	RS232 TX	Transmit Line (RS-232)	O
3	ISO GND	Isolated Signal Ground	IGND

<b>AUX ENCODER - Auxiliary Feedback Connector</b>			
Pin	Name	Description / Notes	I/O
1	RESERVED	Reserved	-
2	RESERVED	Reserved	-
3	RESERVED	Reserved	-
4	PDI-8 + (AUX ENC A+ / CAP-2)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture	I
5	PDI-8 - (AUX ENC A-)	Programmable Digital Input or Auxiliary Encoder (For Differential Signals Only)	I
6	PDI-9 + (AUX ENC B+ / CAP-2)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture	I
7	PDI-9 - (AUX ENC B-)	Programmable Digital Input or Auxiliary Encoder (For Differential Signals Only)	I
8	PDI-10 + (AUX ENC I+ / CAP-1)	Programmable Digital Input or Auxiliary Encoder or High Speed Capture	I
9	PDI-10 - (AUX ENC I-)	Programmable Digital Input or Auxiliary Encoder (For Differential Signals Only)	I
10	SGN GND	Signal Ground	SGND
11	SGN GND	Signal Ground	SGND
12	SGN GND	Signal Ground	SGND
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-4 +	Differential Programmable Analog Input	I
15	PAI-4 -		I

<b>COMM - CAN Communication Connector</b>			
Pin	Name	Description / Notes	I/O
1	CAN_H	CAN_H Line (Dominant High)	I
2	CAN_L	CAN_L Line (Dominant Low)	I
3	CAN_GND	CAN Ground	CGND
4	RESERVED	Reserved	-
5	RESERVED	Reserved	-
6	RESERVED	Reserved	-
7	CAN_GND	CAN Ground	CGND
8	RESERVED	Reserved	-

<b>DC BUS - Power Connector</b>			
Pin	Name	Description / Notes	I/O
1	DC-	Internal DC Bus Voltage (Can Be Used To Connect External Shunt Regulator)	O
2	DC-		O
3	DC+		O
4	DC+		O

<b>FEEDBACK - Feedback Connector</b>			
Pin	Name	Description / Notes	I/O
1	COS +	Cosine Input	I
2	COS -		I
3	SIN +	Sine Input	I
4	SIN -		I
5	SGN GND	Signal Ground	SGND

6	HALL A+	Commutation Sensor Input (For Single-Ended Signals Leave Negative Terminal Open)	I
7	HALL A-		I
8	HALL B+	Commutation Sensor Input (For Single-Ended Signals Leave Negative Terminal Open)	I
9	HALL B-		I
10	RESERVED	Reserved	-
11	HALL C+	Commutation Sensor Input (For Single-Ended Signals Leave Negative Terminal Open)	I
12	HALL C-		I
13	+5V OUT	+5V Encoder Supply Output (Short Circuit Protected)	O
14	PAI-3	Programmable Analog Input	I
15	RESERVED	Reserved	-

**I/O - Signal Connector**

Pin	Name	Description / Notes	I/O
1	PDO-1	Isolated Programmable Digital Output	O
2	OUTPUT COMMON	Digital Output Common	OGND
3	PDO-2	Isolated Programmable Digital Output	O
4	PAI-1 + (REF+)	Differential Programmable Analog Input or Reference Signal Input	I
5	PAI-1 - (REF-)		I
6	PAI-2	Programmable Analog Input	I
7	PAO-1	Programmable Analog Output	O
8	OUTPUT PULL-UP	Digital Output Pull-Up	I
9	PDI-5	Isolated Programmable Digital Input	I
10	PDO-3	Isolated Programmable Digital Output	O
11	PDI-1	Isolated Programmable Digital Input	I
12	PDI-2	Isolated Programmable Digital Input	I
13	PDI-3	Isolated Programmable Digital Input	I
14	PDO-4	Isolated Programmable Digital Output	O
15	INPUT COMMON	Digital Input Common (Can Be Used To Pull-Up Digital Inputs)	IGND
16	SGN GND	Signal Ground	SGND
17	PDI-4	Isolated Programmable Digital Input	I
18	PDI-6	Isolated Programmable Digital Input	I
19	PDI-7	Isolated Programmable Digital Input	I
20	ENC A+ OUT	Emulated Encoder Channel A Output	O
21	ENC A- OUT		O
22	ENC B+ OUT	Emulated Encoder Channel B Output	O
23	ENC B- OUT		O
24	ENC I+ OUT	Emulated Encoder Index Output	O
25	ENC I- OUT		O
26	SGN GND	Signal Ground	SGND

**MOTOR POWER - Power Connector**

Pin	Name	Description / Notes	I/O
1	PE	Protective Earth Ground	PE
2	MOTOR C	Motor Phase C	O
3	MOTOR B	Motor Phase B	O
4	MOTOR A	Motor Phase A	O

**POWER - Power Connector**

Pin	Name	Description / Notes	I/O
1	PE	Protective Earth Ground	PE
2	AC3	AC Supply Input (Single Or Three Phase)	I
3	AC2		I
4	AC1		I

**HARDWARE SETTINGS**

**Switch Functions**

Switch	Description	Setting	
		On	Off
1	Bit 0 of binary value of drive address/ID.	1	0
2	Bit 1 of binary value of drive address/ID.	1	0
3	Bit 2 of binary value of drive address/ID.	1	0
4	Bit 3 of binary value of drive address/ID.	1	0
5	Bit 4 of binary value of drive address/ID.	1	0
6	Bit 5 of binary value of drive address/ID.	1	0
7	Bit 0 of binary value of drive bit rate setting.	1	0
8	Bit 1 of binary value of drive bit rate setting.	1	0

*Additional Details*

The drive can be configured to use the address and/or bit rate stored in non-volatile memory by setting the address and/or bit rate value to 0. Use the table below to map actual bit rates to a bit rate setting.

Bit Rate (kbits/sec)		Value For Bit Rate Setting
CANopen	RS-485	
Load from non-volatile memory	Load from non-volatile memory	0
500	9.6	1
250	38.4	2
125	115.2	3

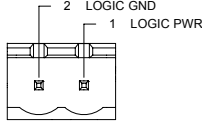
**Jumper Settings**

Jumper	Description	Configuration		
		Not Installed	Pins 1-2	Pins 2-3
J1	Reserved.	-	-	N/A
J2	CAN bus termination. Install this jumper on the last drive in a CAN network.	Non-terminating Node	Terminating Node	N/A

**MECHANICAL INFORMATION**

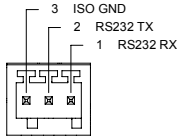
**+24V LOGIC - Logic Power Connector**

Connector Information	2-port, 5.08 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix Contact: P/N 1757019



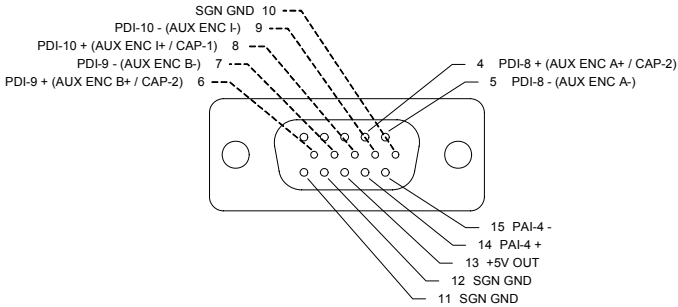
**AUX COMM - RS232 Communication Connector**

Connector Information	3-pin, 2.5 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix: Plug P/N 1881338



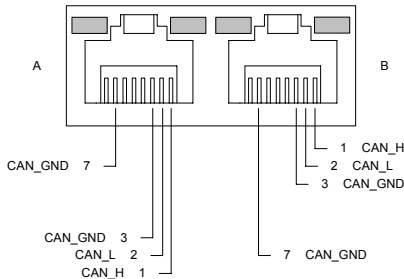
**AUX ENCODER - Auxiliary Feedback Connector**

Connector Information	15-pin, high-density, male D-sub
Mating Connector	AMP: Plug P/N 748365-1; Housing P/N 748677-1; Terminals P/N 748610-4 (loose) or 748610-2 (strip)



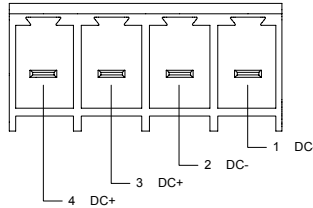
**COMM - CAN Communication Connector**

Connector Information	Shielded, dual RJ-45 socket with LEDs
Mating Connector	AMP: Plug P/N 5-569552-3



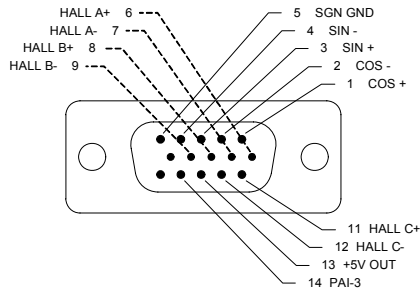
**DC BUS - Power Connector**

Connector Information	4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix Contact: P/N 1804920



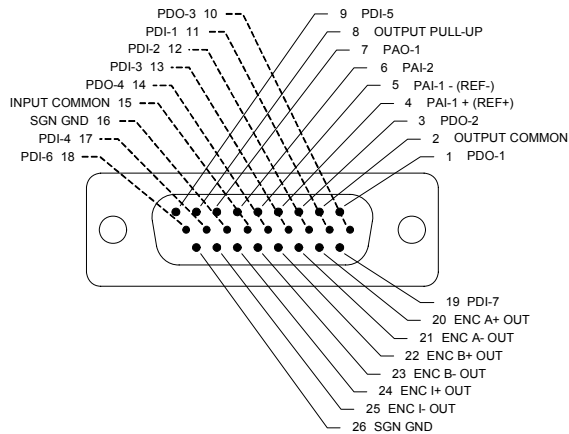
**FEEDBACK - Feedback Connector**

Connector Information	15-pin, high-density, female D-sub
Mating Connector	AMP: Plug P/N 748365-1; Housing P/N 748677-1; Terminals P/N 748333-4 (loose) or 748333-2 (strip)



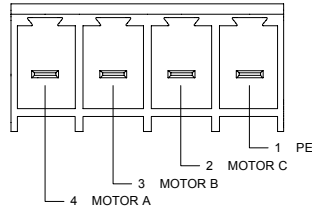
**I/O - Signal Connector**

Connector Information	26-pin, high-density, female D-sub
Mating Connector	AMP: Plug P/N 748365-1; Housing P/N 748677-2; Terminals P/N 748333-4 (loose) or 748333-2 (strip)



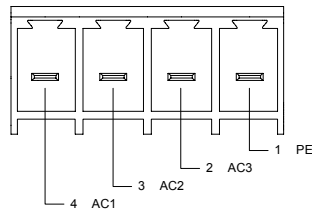
**MOTOR POWER - Power Connector**

Connector Information	4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix Contact: P/N 1804920



**POWER - Power Connector**

Connector Information	4-port, 7.62 mm spaced, enclosed, friction lock header
Mating Connector	Phoenix Contact: P/N 1804920



**PART NUMBERING INFORMATION**

Example: **D P R A N I E - 0 1 5 A 4 0 0 -**

Drive Series
DP DigiFlex Performance

Communication
R RS232/RS485
C CANopen or RS232
Q SynqNet

Command Inputs
AN Analog (±10V) No Step & Direction
AL Analog (±10V) Low Voltage Step & Direction (5V)
AH Analog (±10V) High Voltage Step & Direction (24V)
NL No Analog Low Voltage Step & Direction (5V)
NN No Analog, No Step & Direction (Communication Interface Only)

Digital I/O
I Isolated (24V)
T TTL (5V) Non-Isolated

Motor Feedback
E Incremental Encoder and/or Halls
R Resolver
A Absolute Sin/Cos (Hiperface & Endat)
S Sin/Cos with Halls

Customer Special
Code used to identify customer specials

Revision
A through Z (letters may be skipped)

Max DC Bus Voltage (V <sub>DC</sub> )
080 80
200 200
400 400
600 600

Power and Logic Supply
A AC Input +24V <sub>DC</sub> User Logic Supply Required
N AC Input Only No Logic Supply Required (Internal Supply)
B DC Input Both Logic Supply Options (Internal or User)
L DC Input Logic Supply Required
D DC Input Only Internal Logic Supply

Peak Current (A <sub>0 to Peak</sub> )
015 15
016 16
020 20
025 25
030 30
040 40
060 60
100 100

DigiFlex® Performance™ series of products are available in many configurations. All models listed on the website are readily available, standard product offerings. Other combinations or possibilities can be made available for OEMs with volume requests of 100 or more. Contact Applications Engineering for further information and details.

All specifications in this document are subject to change without written notice. Actual product may differ from pictures provided in this document.